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- 5.2 Minimum Cost Flow Problem
- 5.3 Shortest-Path Problem
- 5.4 Minimum Spanning Tree Problem
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Terminology

- a graph or network is an ordered pair G=(V,A) where V={1,2,...,n} is a set of points called nodes or vertices and A={a₁,a₂,...,a_m} is a set of lines connecting pairs of nodes, a_k=(i,j) where i,j ∈ V.
- the lines are called arcs if they are <u>directed</u> (i.e. have orientation an arrow indicates direction);
- the lines are called edges if they are <u>undirected;</u>
- an arc/edge $(i,j) \in A$ is **incident** to *i* and *j*;
- G=(V,A) is a **directed network** if all the elements of A are arcs;
- G=(V,A) is an **undirected network** if all the elements of A are edges;
- if *A* has both arcs and edges it is a mixed network (any mixed or undirected network may be converted into a directed network);



- if $(i,j) \in A$ is an arc, then *i* is the initial node of (i,j) and *j* is the final node of (i,j), being *j* the sucessor of *i* and *i* the predecessor of *j*.
- if $(i,j) \in A$ is an **edge**, then *i* and *j* are **extremities** of (i,j) and *i* and *j* are **adjacent nodes**.
- a path between two nodes is a sequence of distinct arcs/edges connecting these nodes;
- a directed path from node *i* to node *j* is a path toward node *j*;
- an undirected path from node *i* to node *j* is a sequence of connecting arcs/edges whose direction (if any) can be either toward or away from node *j*;
- a cycle is a path that begins and ends in the same node;



- two nodes are connected if the network contains at least one undirected path between them;
- a **connected network** is a network where every pair of nodes is connected;
- a tree is a connected network with no cycles;
- a **spanning tree** of *G*=(*V*,*A*) is a tree with the same set of nodes *V* and edges belonging to *A*;
- to each arc/edge and each node may also be associated real parameters that are problem dependent, representing: time, capacity, distance, probabilities, supply, demand, flow, length...;
- a **supply node** (or source node or origin) is a node where the flow out exceeds the flow into the node;
- a **demand node** (or sink node or destination) a node where the flow into exceeds the flow out the node;
- a transshipment node (or intermediate node) is a node where the flow in equals the flow out, that is, there is *conservation of flow*;



The Minimum Cost Flow Problem (MCFP)

Let G=(V,A) a <u>directed and connected</u> network with *at least one supply node* and *at least* one demand node, being the remaining nodes transshipment nodes. Determine how to send the available supply of a commodity through the network so as to satisfy the demand, respecting arc capacities, at minimum cost.

Data:

G=(V,A) directed and connected network;

To each arc $(i,j) \in A$ two parameters are associated:

 u_{ij} the arc capacity, i.e., the maximum value of flow that may traverse it (real $u_{ij} \ge 0$) c_{ij} the cost per unit flow through the arc

To each node, $i \in V$, is associated the parameter b_i : $b_i = \text{net flow generated at node } i$ = flow out node i - flow into node i



The value of b_i depends on the nature of node *i*, where

 $b_i > 0$ if node *i* is a supply node,

 $b_i < 0$ if node *i* is a demand node,

 $b_i=0$ if node *i* is a transshipment node.

Assumptions:

1) arc capacities are compatible with supplies and demands;

2) the problem is balanced: the total supply equals the total demand: $\sum_{i \in V} b_i = 0$

Let x_{ij} be the amount of flow (units of the commodity) through arc $(i,j) \in A$ and Z the total cost of sending the available supply through the network.

The LP formulation for the MCFP is:

$$\operatorname{Min} Z = \sum_{(i,j) \in A} c_{ij} x_{ij}$$

s.t.
$$\begin{bmatrix} \sum_{j \in V} x_{ij} - \sum_{k \in V} x_{ki} = b_i, & \forall i \in V \\ 0 \leq x_{ij} \leq u_{ij}, & \forall (i,j) \in A \end{bmatrix}$$

For the network formulation of the MCFP:

Identify the network optimisation problem to solve; design the network G(V,A). Associate to each arc (i,j) the parameters (c_{ij},u_{ij}) and to each node *i* the parameter b_i identifying the supply and the demand nodes.

Define the variable x_{ij} and the objective.



Properties of the MCFP

Property 1: The MCFP has, at least, a feasible solution.

Corollary: The MCFP has an optimal solution.

Property 2: A MCFP where every b_i and u_{ij} are integer values has, at least, one optimal

solution with all variables assuming integer values.

Applications:

- management of passenger traffic
- production management and distribution of commodities
- personnel scheduling
- planning the distribution of fluids (water, gas, oil)

Special cases of MCFP: Transportation Problem (MCFP without transshipment nodes, and with no capacity constraints); Assignment Problem and others.



Resolution methods for the MCFP

- Algorithm for LP (for example, the Simplex Method solver/excel)
- The Network Simplex Method;
- The Out of Kilter Method;
- ...

Variants of the MCFP

• Total Supply > Total Demand:

The net flow at the sources is a maximum value that must be respected, and the constraints at the sources should be of type " \leq ".

• Total Supply < Total Demand:

The net flow at the sinks is a minimum value that must be respected, and the constraints at the sink nodes should be of type " \geq ".



Resolution of the MCFP with the Solver/Excel

Prototype example 1 – Distribution Unlimited Co. (HL, & 3.4, pp. 58)

		А	В	С	D	E	F	G	H		J	K	
	1 p	blem - Dist	tribution Unli	imited Co.									
	2												
	3												
	4	ar	CS										
	5	from	to	flow		capacity	unit c		nodes	from-to		supply/demand	
	6	F1	F2	0	<=	10	200		F1	0	=	50	
	7	F1	DC	0			400		F2	0	=	40	
	8	F1	W1	0			900		DC	0	=	0	
	9	F2	DC	0			300		W1	0	=	-30	
	10	DC	W2	0	<=	80	100		W2	0	=	-60	
	11	W1	W2	0			300						
	12	W2	W1	0			200)					
	13												
	14		total cost	0				=SUMIF	from;H6;\$	C\$6:\$C\$1	2)-Sl	JMIF(to;H6;\$C\$6:\$	\$C\$12)
								=SUMIF	from;H7;\$	C\$6:\$C\$1	2)-Sl	JMIF(to;H7;\$C\$6:\$	\$C\$12)
Define names: (forr	mu	lac tah		V				=SUMIF	from;H8;\$	C\$6:\$C\$1	2)-Sl	JMIF(to;H8;\$C\$6:\$	\$C\$12)
•			=SUMI	PRODUCT(f	flow;unit_cost) =SUMIF(from;H9;\$C\$6:\$C\$12)-SUMIF(to;H9;\$C\$6:\$C\$12)								
from= A6	from= A6:A12 to= B6:B12							=SUMIF(from;H10;\$C\$6:\$C\$12)-SUMIF(to;H10;\$C\$6:\$C\$12					
to= B6:B1													
flow= C6:	C12	7											
unit_cost	= F	0:F12											

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Network optimization - MCFP

Resolution of the MCFP with the

Prototype example 1 – Distribut

	Α	В
1	oblem - Dis	tribution (
2		
3		
4	ar	cs
5	from	to
6	F1	F2
7	F1	DC
8	F1	W1
9	F2	DC
10	DC	W2
11	W1	W2
12	W2	W1
13		
14		total co
45		

Se <u>t</u> Objective:	\$C\$13			
То: <u>М</u> ах @	Mi <u>n</u>	◎ <u>V</u> alue Of:	0	
By Changing Variable Cells:				
flow				
Subject to the Constraints:				
\$C\$10 <= \$E\$10 \$C\$6 <= \$E\$6 \$I\$6:\$I\$10 = \$K\$6:\$K\$10			*	Add
\$1\$0.\$1\$10 - \$K\$0.\$K\$10				Change
				Delete
				Reset All
			-	Load/Save
Make Unconstrained Varia	bles Non-N	egative		
Select a Solving Method:	Simp	olex LP	•	Options
Solving Method Select the GRG Nonlinear en- engine for linear Solver Prob non-smooth.				



The Shortest-Path Problem (SPP)

Let G=(V,A) a <u>directed and connected</u> network with only one origin and only one destination. Associated to each arc $(i,j) \in A$ is a nonnegative real number c_{ij} that represents the length between nodes *i* and *j*. Find the shortest path (the path with the minimum total length) from the origin node to the destination node.

Data:

G=(V,A) directed and connected network; $s \in V$ the origin; $t \in V$ the destination

 $c_{ii} > 0$ length (or cost, or distance) of arc $(i,j) \in A$

For the network formulation of the SPP:

Identify the network G=(V,A), as well as the origin, the destination and all the lengths (c_{ii}) , the problem to solve and the objective.

For the LP formulation of the SPP:

define variables $x_{ij} = \begin{cases} 1 & \text{if arc } (i,j) \text{ is in the path} \\ 0 & \text{otherwise} \end{cases}$

Z – total length of the path from **s** to **t** (the sum of the length of all arcs in the path)

$$\operatorname{Min} Z = \sum_{(i,j) \in A} c_{ij} x_{ij}$$
s.t.
$$\begin{bmatrix} \sum_{j:(s,j) \in A} x_{sj} = 1 \\ \sum_{i:(i,t) \in A} x_{it} = 1 \\ \sum_{j:(i,j) \in A} x_{ij} = \sum_{k:(k,i) \in A} x_{ki} \quad \forall i \in V \setminus \{s,t\} \\ x_{ij} \in \{0,1\}, \qquad \forall (i,j) \in A \end{bmatrix}$$

The first two constraints ensure that the path starts at the origin, *s*, and ends at the destination, *t*. The third set of restrictions defines the remaining nodes as nodes that may be used to form the path.



The SPP is a particular case of the Minimum Cost Flow Problem where:

$$u_{ij} = 1, \quad \forall (i, j) \in A$$
$$b_s = 1$$
$$b_t = -1$$
$$b_i = 0, \quad \forall i \in V, \quad i \neq s, t$$

Property (integer solutions):

In the LP model for the SPP, if each $x_{ij} \in \{0,1\}$ is substituted by $x_{ij} \ge 0$, then at least one optimal solution exists with all variables assuming integer values.



Resolution of the SPP with the Solver/Excel

Prototype example 2 – Seervada Park 1st (HL, chap 9.3 pp. 364)

	А	В	С	D	E	F	G	Н	I. I.	J			
1	Se												
2													
3	From	to	solution	distance		node	total		Supply/Demand				
4	0	Α	0	2		0	0	=	1				
5	0	В	0	5		Α	0	=	0				
6	0	С	0	4		В	0	=	0				
7	Α	В	0	2		С	0	=	0				
8	Α	D	0	7		D	0	=	0				
9	В	Α	0	2		E	0	=	0				
10	В	С	0	1		Т	0_	=	-1				
11	В	D	0	4									
12	В	E	0	3			Ļ						
13	С	В	0	1					total				
14	С	E	0	4		=SUM	IF(\$A\$4:\$A	\$18;F4	l;\$C\$4:\$C\$18)-SUM	IF(\$B\$4:\$B	\$18;F4	1;\$C\$4:\$C!	\$18)
15	D	E	0	1					;\$C\$4:\$C\$18)-SUM				
16	D	Т	0	5		=SUM	IF(\$A\$4:\$A	\$18;F6	;\$C\$4:\$C\$18)-SUM	IF(\$B\$4:\$B	\$18;F6	5;\$C\$4:\$C!	\$18)
17	E	D	0	1		=SUMIF(\$A\$4:\$A\$18;F7;\$C\$4:\$C\$18)-SUMIF(\$B\$4:\$B\$18;F7;\$C\$4:\$C\$18)							
18	E	Т	0	7		=SUMIF(\$A\$4:\$A\$18;F8;\$C\$4:\$C\$18)-SUMIF(\$B\$4:\$B\$18;F8;\$C\$4:\$C\$18)							
19							-);\$C\$4:\$C\$18)-SUM	-			-
20	TO	TAL DISTA	NCE	0		=SUMIF(\$A\$4:\$A\$18;F10;\$C\$4:\$C\$18)-SUMIF(\$B\$4:\$B\$18;F10;\$C\$4:\$C\$18							
21													

=SUMPRODUCT(C4:C18;D4:D18)



Resolution of the SPP with the *Solver/Excel*

Prototype example 2 – Seervada Park 1st (HL, chap 9.3 pp. 364)

	Α	В	С	D	Е	F	G	Solver Parameters
1	Se	ervada Pa	rk					
2								Set Objective: \$D\$20
3	From	to	solution	distance		node	total	To: Max Min Value Of: 0
4	0	А	0	2		0	0	To: O Max O Min O Value Of:
5	0	В	0	5		Α	0	By Changing Variable Cells:
6	0	С	0	4		В	0	\$C\$4:\$C\$18
7	Α	В	0	2		С	0	Subject to the Constraints:
8	Α	D	0	7		D	0	\$G\$4:\$G\$10 = \$I\$4:\$I\$10
9	В	А	0	2		E	0	Change
10	В	С	0	1		Т	0	
11	В	D	0	4				Delete
12	В	E	0	3				Reset All
13	С	В	0	1				
14	С	E	0	4				- Load/Save
15	D	E	0	1				Make Unconstrained Variables Non-Negative
16	D	Т	0	5				Select a Solving Method: Simplex LP Options
17	E	D	0	1				Solving Method
18	E	Т	0	7				Select the GRG Nonlinear engine for Solver Problems that are smooth nonlinear. Select the LP Simplex
19								engine for linear Solver Problems, and select the Evolutionary engine for Solver problems that are non-smooth.
20	тот	TAL DISTAN	NCE	0				
21								<u>H</u> elp <u>Solve</u> Cl <u>o</u> se



	А	В	С	D	Е	F	G	Н	I
1	Se								
2									
3	From	to	solution	distance		node	total		Supply/Demand
4	0	Α	1	2		0	1	=	1
5	0	В	0	5		Α	0	=	0
6	0	С	0	4		В	0	=	0
7	А	В	1	2		С	0	=	0
8	Α	D	0	7		D	0	=	0
9	В	Α	0	2		E	0	=	0
10	В	С	0	1		Т	-1	=	-1
11	В	D	1	4					
12	В	E	0	3					
13	С	В	0	1					
14	С	E	0	4					
15	D	E	0	1					
16	D	Т	1	5					
17	E	D	0	1					
18	E	Т	0	7					
19									
20	TO	TAL DISTAN	NCE	13					



Minimum Spanning Tree Problem (MSTP)

Given an **undirected** and **connected** network, with lengths associated to the edges, choose the set of edges that represent a spanning tree (a tree including all network nodes) with minimum total length.

Data:

G=(V,A) <u>undirected</u> network; $c_{ii} > 0$ length (or cost, or distance) of edge $(i,j) \in A$

For the network formulation of the MSTP:

Identify the network, G=(V,A), as well as all the lengths (c_{ij}) and the problem to solve.

Property : A spanning tree of a network with *n* nodes has the same *n* nodes and n-1 edges (no cycles).

Prim Algorithm (1957) determines the minimum spanning tree of G.

Objective for iteration *k* - Select the node that is not yet in the tree and is the closest to the tree. Link the node to the tree.

Repeat until all the nodes are in the tree.



PRIM's Algorithm

O. Input: Undirected connected network with *n* nodes G=(V,A); Lengths of the edges;

1. Initialisation

Choose any node and the shortest edge incident on it; Initialise the tree with the edge and respective nodes;

 $k \leftarrow 2;$

2. Iteration k

If all the nodes are in the tree (k=n), go to step 3.

otherwise, select the shortest edge linking a node outside the tree to a node

already in the tree;

Add the edge to the tree;

 $k \leftarrow k+1;$

Go to step 2.

3. Draw the minimum spanning tree and determine the total length of the tree. **Stop.**



Resolution of the MSTP with the Prim Algorithm

Prototype example 2– SEERVADA PARK, 2^{nd} – network with n=7 nodes $\Rightarrow n-1=6$ iterations.

iteration	nodes in	closest and adjacent	edge	edge to include in the		
	the tree	node ∉ tree	length	tree		

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	iteration	nodes in the tree	closest and adjacent node ∉ tree	edge length	edge to include in the tree	Instituto Superior de Economia e Gestão UNIVERSIDADE TÉCNICA DE LISBOA	
	1	0	А	2	(O,A)		
	2	0	С	4			
	2	А	В	2	(A,B)		
ſ	3	0	С	4		Minimum Spanning Tree	
		А	D	7	(B,C)		
		В	С	1			
		0	-				
	4	А	D	7	(D E)	it.1 it.2 it.6	
	4	В	E	3	(B,E)	O B D	
		С	E	4		$1 \qquad 3 \qquad 1$	
		А	D	7		it.3 it.4 it.5	
	5	В	D	4		(C) (E)	
	Э	С	-		(E,D)	The total MST length is 14	
		E	D	1			
	6	D	Т	5			
	6	E	Т	7	(D,T)	24	